

# Vak: Robot Control - Mechatronics

credits: 15

Vakcode ELVB23RCM

Naam Robot Control - Mechatronics

Studiejaar 2023-2024 ECTS credits 15

Taal Engels
Coördinator F. Martins

Werkvormen Hoorcollege

Opdracht

Practicum / Training

**Toetsen** Robot Control - Mechatronics - Opdracht

### Leeruitkomsten

Design: The starting professional considers various solutions in order to arrive at a detailed and well-founded (electro)technical product/service/process based on the program of requirements, making use of appropriate design methods and taking social interests and engineering standards into account.

Realization: The starting professional realizes and validates a (prototype of a) product/service/process based on an (electrical) technical design and makes appropriate use of materials/techniques/instruments.

Management: The starting professional can professionally set-up, execute, plan, adjust and deliver a small-scale project on time.

#### Inhoud

This course is focused on the simulation, assembly and control of robots to perform a predefined task.

Topics include: programming of a microcontroller board to implement the robot control, different sensors to measure internal and external variables (for example in robot localization, navigation and obstacle avoidance), mathematical modeling and simulation. Concepts of controllers (like PID) are reviewed and applied in the context of go-togoal, path following, trajectory-tracking controllers for mobile robots. Different techniques to control mobile robots are discussed, like behavior-based robotics, behavior trees and/or finite statemachines.

Students will work in groups and may focus on specific topics depending on their major/specialization. They need to manage their own project work (for instance project plan/milestones/scrum, budget, role definition, presenting etc.), document their results (in English – B2 level) and demonstrate their working prototype.

## Opgenomen in opleiding(en)

Elektrotechniek Major Mechatronica

### School(s)

Instituut voor Engineering