

Vak: Robot Control - Sensor Technology

credits: 15

Vakcode ELVB23RCS
Naam Robot Control - Sensor Technology
Studiejaar 2023-2024
ECTS credits 15
Taal Engels
Coördinator F. Martins

Werkvormen Hoorcollege
 Opdracht
 Practicum / Training
Toetsen Robot Control - Sensor Technology -
 Opdracht

Leeruitkomsten

Design: The starting professional considers various solutions in order to arrive at a detailed and well-founded (electro)technical product/service/process based on the program of requirements, making use of appropriate design methods and taking social interests and engineering standards into account.

Realization: The starting professional realizes and validates a (prototype of a) product/service/process based on an (electrical) technical design and makes appropriate use of materials/techniques/instruments.

Management: The starting professional can professionally set-up, execute, plan, adjust and deliver a small-scale project on time.

Inhoud

This course is focused on the simulation, assembly and control of robots to perform a predefined task.

Topics include: programming of a microcontroller board to implement the robot control, different sensors to measure internal and external variables (for example in robot localization, navigation and obstacle avoidance), mathematical modeling and simulation. Concepts of controllers (like PID) are reviewed and applied in the context of go-to-goal, path following, trajectory-tracking controllers for mobile robots. Different techniques to control mobile robots are discussed, like behavior-based robotics, behavior trees and/or finite state-machines.

Students will work in groups and may focus on specific topics depending on their major/specialization. They need to manage their own project work (for instance project plan/milestones/scrum, budget, role definition, presenting etc.), document their results (in English - B2 level) and demonstrate their working prototype.

Opgenomen in opleiding(en)

Elektrotechniek Major Sensor Technology

School(s)

Instituut voor Engineering

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